VERSION WITH MARKINGS TO SHOW CHANGES MADE

IN THE CLAIMS

The following claims have been added:

78. A method comprising:

receiving a current frame comprising a frame sync segment and a plurality of data segments, wherein the current frame contains a current map indicating a location of data in a first frame, a next map indicating a location of data in a second frame, and a count indicating the number of frames until the next map becomes the current map; and,

processing the data in the first frame in response to the current map.

79. The method of claim 78 wherein the current map, the next map, and the count are contained in the same segment of the current frame.

80. The method of claim 79 wherein the segment containing the current map, the next map, and the count comprises a data segment of the current frame.

81. The method of claim 78 further comprising:

maintaining a count related to when the next map will change to the current map; and,

counting down from the count based on frame times.

82. The method of claim 81 wherein the current map, the next map, and the count are contained in the same segment of the current frame.

83. The method of claim 82 wherein the segment containing the current map, the next map, and the count comprises a data segment of the current frame.

84. The method of claim 78 wherein the first frame is the current frame, and wherein the second frame is a future frame.

85. A method of transmitting a current frame having a frame sync segment and a plurality of data segments comprising:

inserting a current map, a next map, and a count into the current frame, wherein the current map indicates a location of data in a first frame, wherein the next map indicates a location of data in a second

frame, and wherein the count indicates the number of frames until the next map becomes the current map; and, transmitting the current frame.

86. The method of claim 85 wherein the current map, the next map, and the count are contained in the same segment of the current frame.

87. The method of claim 86 wherein the segment containing the current map, the next map, and the count comprises a data segment of the current frame.

88. The method of claim 85 wherein the first frame is the current frame, and wherein the second frame is a future frame.

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